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## Short Papers

### New Method for Computing the Resonant Frequencies of Dielectric Resonators

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**Abstract**—A new method is developed for accurately predicting resonant frequencies of dielectric resonators used in microwave circuits. By introducing an appropriate approximation in the field distribution outside the resonator, an analytical formulation becomes possible. Two coupled eigenvalue equations thus derived are subsequently solved by a numerical method. The accuracy of the results computed by the present method is demonstrated by comparison with previously published data.

#### I. INTRODUCTION

Dielectric resonators made of high permittivity material have found practical applications in microwave circuits due mainly to their high-*Q* values. The dominant  $TE_{01\delta}^0$  mode in the low-profile cylindrical resonators [Fig. 1(a)] has traditionally been analyzed by using the so-called magnetic wall model, in which the cylindrical surface containing the circumference of the resonator is replaced with a fictitious open-circuit boundary

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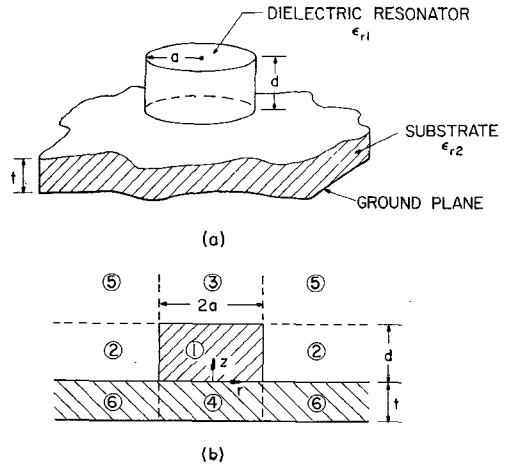


Fig. 1. (a) Dielectric resonator. (b) Side view of dielectric resonator.

(magnetic wall) [1]. Recently, Konishi *et al.* [2] reported a more accurate method based on the variational procedure for computing the resonant frequency of  $TE_{01\delta}^0$  modes. Their predicted resonant frequencies agree with experimental data within 1 percent [2]. On the other hand, the magnetic wall method typically gives rise to numerical values smaller than the experimental by about 10 percent.

The method reported by Garault and Guillon [4] is also capable of predicting the resonant frequency with less than 1 percent error. In their method, successive application of imperfect magnetic wall conditions on side and end walls results

in the dielectric resonator of effective height and radius. From this process, an accurate resonant frequency is obtained.

In this short paper, a simple numerical procedure is reported for predicting the resonant frequencies of  $TE_{01\delta}^0$  modes in cylindrical dielectric resonators. The method is based on the semianalytical technique originally developed by Marcatili [3] for analyzing the propagation characteristics of a rectangular dielectric waveguide, and extended here to apply to the three-dimensional cylindrical resonator structure. Although slight modifications of the formulation make it possible to analyze rectangular resonators [1] as well, such extensions are not included here.

## II. METHOD OF ANALYSIS

In Fig. 1(a), a typical dielectric resonator is placed on a dielectric substrate which is in turn backed by a ground plane. The relative dielectric constant  $\epsilon_{r1}$  of the resonator is much higher than that of the substrate  $\epsilon_{r2}$ . When  $\epsilon_{r2} = 1$  and the substrate thickness  $t$  becomes infinity, the structure represents the resonator in free space as analyzed in [1] and [2].

The major difficulty in the analysis of dielectric resonators lies in the fact that the structure as shown in Fig. 1 does not belong to a separable geometry. The rigorous analysis requires quite complicated formulations. However, it is possible to introduce a simplification which leads to a pair of conventional eigenvalue equations. This simplification arises from observing that in a high- $Q$  resonator most of the electromagnetic energy is stored in region 1 [see Fig. 1(b)] and the field decays exponentially in regions 2-4. A small amount of energy is in 2-4 and even less is in regions 5 and 6. Therefore, only a small error is introduced in the calculation of resonant characteristics if one ignores the field in 5 and 6 and removes the requirement of matching the field between regions 2 and 5, 6, etc. It is now necessary to match the field only on the boundary surfaces of region 1.

For TE modes which have no circumferential variation, the  $H_z$  field in each region may be written as

$$H_z = \begin{cases} A_1 \sin \beta(z - z_0) J_0(hr) & \text{region 1} \\ A_2 \sin \beta(z - z_0) K_0(pr) & \text{region 2} \\ A_3 \exp[-\gamma(z - d)] J_0(hr) & \text{region 3} \\ A_4 \sinh[\xi(z + t)] J_0(hr) & \text{region 4} \end{cases} \quad (1a)$$

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$$H_z = \begin{cases} A_1 \sin \beta(z - z_0) J_0(hr) & \text{region 1} \\ A_2 \sin \beta(z - z_0) K_0(pr) & \text{region 2} \\ A_3 \exp[-\gamma(z - d)] J_0(hr) & \text{region 3} \\ A_4 \sinh[\xi(z + t)] J_0(hr) & \text{region 4} \end{cases} \quad (1c)$$

$$H_z = \begin{cases} A_1 \sin \beta(z - z_0) J_0(hr) & \text{region 1} \\ A_2 \sin \beta(z - z_0) K_0(pr) & \text{region 2} \\ A_3 \exp[-\gamma(z - d)] J_0(hr) & \text{region 3} \\ A_4 \sinh[\xi(z + t)] J_0(hr) & \text{region 4} \end{cases} \quad (1d)$$

where

$$\begin{aligned} \beta^2 &= \epsilon_{r1} k_0^2 - h^2 = k_0^2 + p^2 \\ \gamma^2 &= h^2 - k_0^2 \quad \xi^2 = h^2 - \epsilon_{r2} k_0^2 \\ k_0 &= \omega_0 \sqrt{\epsilon_0 \mu_0} \end{aligned} \quad (2)$$

and  $z_0$ ,  $A_1$ ,  $A_2$ ,  $A_3$ , and  $A_4$  are constants to be determined.  $J_0$  and  $K_0$  are the Bessel and the modified Hankel functions of order zero.  $\omega_0$  is the angular resonant frequency. All the field components can easily be derived from (1). Note that  $E_z = E_r = H_\theta = 0$  for TE modes with no circumferential field variation.

The next task is to apply the continuity conditions on  $H_z$  and  $E_\theta$  at  $r = a$ ,  $0 < z < d$ , and  $E_\theta$  and  $H_r$  at  $z = 0$  and  $d$ ,  $0 < r < a$ . When this is done,  $A_1$ - $A_4$  and  $z_0$  can be eliminated to yield two coupled eigenvalue equations

$$\left\{ \frac{J_0'(ha)}{hJ_0(ha)} + \frac{K_0'(pa)}{pK_0(pa)} = 0 \right. \quad (3a)$$

$$\left. \begin{aligned} \beta d &= q\pi + \tan^{-1}\left(\frac{\gamma}{\beta}\right) \\ &+ \tan^{-1}\left(\frac{\xi}{\beta} \coth \xi t\right), \quad q = 0, 1, 2, \dots \end{aligned} \right. \quad (3b)$$

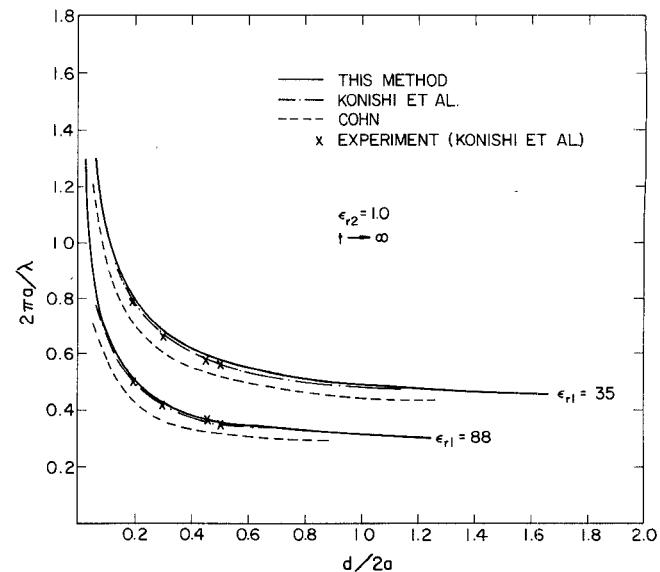


Fig. 2. Numerical results of the resonant frequency.

where the principal branches are to be taken for the arctangent functions. The primes in (3a) indicate differentiation with respect to arguments. Equations (3a) and (3b) together with (2) are then solved for the resonant frequency  $\omega_0$ . It should be noted that, in the magnetic wall model (3a) is replaced with

$$J_0(ha) = 0. \quad (4)$$

This equation is the consequence of the imposition of the artificial open boundary condition on the cylindrical surface. This oversimplification caused the predicted resonant frequencies in [1] to be substantially lower than the experimental data.

Before concluding this section, let us discuss the designation of the mode index. For a given  $k_0$ , (3a) has a finite number of roots which correspond to different radial field distributions. The orders of these roots are numbered with the index  $m$  starting from 1. On the other hand, the field variation in the axial ( $z$ ) direction is governed by the index  $q$ . In the circumferential direction, the field does not vary and hence the index takes only the value zero. The resonant modes are now designated as  $TE_{0mq}$ , and the dominant mode  $TE_{010}$  is often referred to in the literature [2] as  $TE_{01\delta}^0$ .

## III. NUMERICAL RESULTS

The resonant frequency of the dominant mode in the dielectric resonator placed in free space has been computed. For this case,  $\epsilon_{r2} = 1$  and  $t \rightarrow \infty$ , so that (3b) becomes

$$\beta \tan\left(\frac{\beta d}{2}\right) = \gamma \quad (5)$$

for  $q = 0$ .

In Fig. 2, numerical results for the resonators with the structural parameters identical to those in [2] are plotted. The resonant frequencies predicted by the present method agree favorably with the experimental data and results computed by Konishi *et al.* [2], while those derived by the magnetic wall model are considerably lower. It should also be noted that the agreement between the present and Konishi's methods is better for  $\epsilon_{r1} = 88$  than  $\epsilon_{r1} = 35$ . This is expected, since the basic assumption of the present method becomes less valid for resonators with lower dielectric constants and hence lower  $Q$ .

#### IV. CONCLUSIONS

A new method has been presented for computing the resonant frequencies of cylindrical dielectric resonators.

Although the method by Konishi *et al.* [2] is more accurate, particularly for resonators with lower dielectric constants, their method is considerably more complicated than the present one. The method in [4] is also more complicated than the present one. With almost the same order of simplicity in formulation and computational labor as the magnetic wall model [1], the present method provides results in close agreement with data reported in [2].

#### ACKNOWLEDGMENT

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#### Conversion Loss Limitations on Schottky-Barrier Mixers

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**Abstract**—A new set of criteria involving diode area, material parameters, and temperature is introduced for the Schottky-barrier mixer diode that must be considered if its usage is to be extended to the submillimeter wavelength region or cryogenically cooled to reduce the noise contribution of the mixer. It has been well established that, in order to reduce the parasitic loss as the frequency is increased, it is necessary to reduce the area of the diode. What has not been analyzed heretofore is the effect that a reduction in diode area can have on the intrinsic conversion loss  $L_0$  of the diode resulting from its nonlinear resistance. This analysis focuses on the competing requirements of impedance matching the diode to its imbedding circuit and the finite dynamic range of the nonlinear resistance. As a result,  $L_0$  can increase rapidly as the area is reduced. Results are first expressed in terms of dimensionless parameters, and then some representative examples are investigated in detail. The following conclusions are drawn: a large Richardson constant extends the usefulness of the diode to smaller diameters, and hence, shorter wavelengths; cooling a thermionic emitting diode can have a very detrimental effect on  $L_0$ ; impedance mismatching is found, in general, to be a necessity for minimum conversion loss; and large barrier heights are desirable for efficient tunnel emitter converters.

#### I. INTRODUCTION

The metal-semiconductor contact, or Schottky-barrier diode, has a long history of utilization as a mixer element [1], [2]. Its use has progressed to higher and higher frequencies, with the highest frequency recently being demonstrated by Fetterman *et al.*, who observed mixing at 3 THz with a GaAs Schottky diode [3]. For efficient operation at submillimeter wavelengths,

many previously accepted tenets applicable to the design of microwave Schottky diodes must be reexamined.

Mixer conversion loss  $L_c$ , defined as the ratio of available power from the RF source to the power absorbed in the IF load, can be expressed in the form

$$L_c = L_0 L_p, \quad (1)$$

The intrinsic conversion loss  $L_0$  is the loss arising from the conversion process within the nonlinear resistance of the diode and includes the impedance mismatch losses at the RF and IF ports. The parasitic loss  $L_p$  is the loss associated with the parasitic elements of the diode, the junction capacitance, and spreading resistance. Defined as the ratio of total power absorbed by the impedance  $R_m$  of the nonlinear resistance at the signal frequency,  $L_p$  is given by [4]

$$L_p = 1 + R_s/R_m + \omega_1^2 C^2 R_m R_s \quad (2)$$

where  $\omega_1$  is the signal angular frequency and  $C$  is the junction capacitance. The spreading resistance  $R_s$  is the resistance resulting from constriction of current flow in the semiconductor near the contact and is in series with the parallel elements  $C$  and  $R_m$ . Since  $C \propto d^2$  and  $R_s \propto d^{-1}$ , where  $d$  is the diameter of the junction, (2) indicates that  $d$  should be reduced as the frequency of interest is increased. With the development of electron beam fabrication techniques [5], [6], the ability to produce Schottky barriers with dimensions of the order of a few hundred angstroms is imminent. However, the effect of a reduction in area on the intrinsic conversion loss  $L_0$  must also be evaluated to determine overall mixer performance. This consideration is the central topic of this short paper.<sup>1</sup>

The dependence of  $L_0$  on area originates in the impedance requirements the circuit places on the device. In order for the diode, driven by a local oscillator (LO), to couple most efficiently to a circuit with a specified impedance, it must pass approximately the same current, independent of the junction size. Hence reducing the size of the diode increases the current density through the device and, as a consequence, the dc bias voltage  $V_0$  must be increased. Increasing  $V_0$  limits the useful amplitude of the LO voltage  $V_1$  because the current-voltage ( $I$ - $V$ ) characteristic of the junction in the forward direction is only nonlinear for applied voltages less than the barrier height potential  $V_B$  of the metal-semiconductor interface. Since  $V_0 + V_1 \leq V_B$ , decreasing the area serves to limit  $V_1$ , and consequently may increase  $L_0$ .

Because of the inverse relationship between the RF impedance of the diode and the bias current, superior results should be obtained for small areas if the Richardson constant of the semiconductor and the impedance of the circuit are large. The much larger Richardson constant of silicon extends its usefulness to smaller diameters than gallium arsenide. Moreover, it is predicted that the diode should be operated in an impedance mismatched condition; cooling a thermionic emitting diode can have a very detrimental effect on  $L_0$ , and large values of barrier height are desirable for efficient tunnel emitter converters.

From the classical conversion loss equations developed in Section II, specific situations are analyzed in Section III. Optimum coupling between the diode and the circuit is first analyzed. This result is applied to both thermionic emitting n-GaAs and n-Si Schottky diodes operating at 290 and 77 K,

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<sup>1</sup> For examples of  $L_p$  values with Schottky barriers on GaAs, Si, and Ge for wavelengths extending into the submillimeter, the reader is referred to [7].